

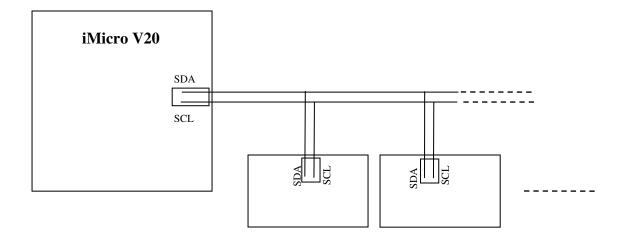
How to connect I²C

By using I^2C bus connector (J14), the iMicro board can be used to control other I^2C slave devices. The only thing you need to change is the I2C_ADD variable defined in MotionCtrl.h.

Note that the address 0x50 is already used for the onboard MM164X motion controller so you have to use different address to communicate with other I^2C compatible controllers.

In one of our application, this iMicro Controller board is connected to Dual Channel DC Motor Driver Module (MHD164) via $\rm I^2C$ bus and we can control 4 DC motors. So if your application need to control more than 2 DC motors, it is possible by connecting to other driver cards via $\rm I^2C$ bus as long as the addresses are properly taken care of.

The following diagram shows how the boards can be connected using I²C bus.



Note that the J14 of iMicro V20 also comes with 5V and GND pin to power external devices.